## Hall Effect, Non-Contacting Position Sensor



#### **Features:**

- Non-contact technology provides clean outputs without sliding contact noise
- Absolute position output through multiple turns
- ± 0.50% independent linearity (± 0.25% is available)
- 10 million shaft rotations minimum life
- Ratiometric output
- 12 mA max current
- -40°C to +125°C operating temperature
- Lead-free
- RoHS 2 compliant



Designed to operate reliably in demanding conditions, the MagnePot 8150 series are available in three, five, and ten turn models. Incorporating Hall effect non-contacting technology means they do not wear out, as in contacting devices, and there is no degradation of the output signal over life, making them ideal for applications where minimal maintenance is required.

The 8150 family features a bushing mount with a 7/8" diameter package and a minimum of 10 million shaft rotations. Servo mount is also available. Optional models with sealed shafts and rear lids for protection from severe environments are also possible. A supply voltage of 5 Vdc is required and the ratiometric output can go from 4% to 96% of the supply voltage. Other output voltage options are also available. These sensors are operational from -40°C to 125°C.

#### **Applications:**

- Joystick controls
- Factory automation
- Medical device positioning
- Vision system position feedback
- Targeting systems
- Aircraft flight and panel controls
- Rotary position sensing
- Motion control feedback

### **Model Styles Available**

| 8151 | 1/8" shaft, 1/4" bushing |
|------|--------------------------|
| 8153 | 1/8" shaft, servo mount  |
| 8154 | 6 mm shaft, 3/8" bushing |
| 8156 | 1/4" shaft, 3/8" bushing |

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| Electrical                                |  |
|---|--|
| Input voltage                             | 4.5 to 5.5 Vdc nominal   |
| Output voltage                            | 0.2 Vdc (4%) to 4.8 Vdc (96%) typical (see Feature Codes table)              |
| Output overvoltage limits                 | 10 Vdc to -0.3 Vdc; output may be shorted to ground or supply without damage |
| Output current                            | ±15mA maximum  |
| Output load                               | 1 k $\Omega$ min., 10 k $\Omega$ typical                                     |
| Supply voltage absolute limits            | 20 Vdc max., -10 Vdc minimum   |
| Independent linearity                     | ±0.5% (0.25% available)  |
| Hysteresis                                | 10° maximum (10 turn), 5° maximum (5 turn), 3° maximum (3 turn)              |
| Resolution                                | 0.88° for 3600° travel, 0.44° for 1800° travel, 0.27° for 1080° travel       |
| Supply current                            | 8.5 mA typical, 12 mA maximum  |
| Dielectric strength                       | 750 V rms  |
| Insulation resistance                     | 1,000 ${\sf Meg}\Omega$ minimum  |
| Electrostatic discharge (ESD)             | Passes 2 kV human body model and 15 kV air discharge                         |
| Bulk current injection (BCI)              | Passes 2-500 MHz at 200 mA   |
| Actual electrical travel                  | Same as mechanical travel  |
| Temperature coefficient of output voltage | ±20 ppm/°C   |

### Mechanical

| Total mechanical travel                     | Up to 3600° continuous   |
|---|--|
| Bearing                                     | Bushing models use bronze sleeve, servo model uses two ball bearings |
| Weight                                      | 0.7 oz. nominal  |
| Panel nut tightening torque                 | 25 in. lb. maximum   |
| Start/run torque (ES option adds 0.5 ozin.) | < 0.1 ozin.  |

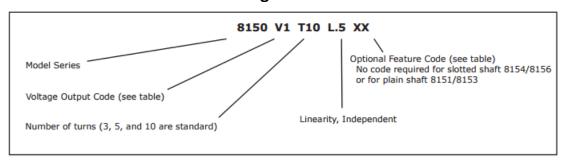
## Hall Effect, Non-Contacting Position Sensor



IP50, IP66 available as option (feature code ES)

| Environmental                |  |
|------------------------------|--|
| Operating temperature range  | -40°C to +125°C  |
| Shock                        | Per MIL R-39023, 6 ms saw-tooth 100 G's  |
| Vibration                    | Per MIL R-39023, 10 G's, 100 to 500 Hz   |
| Moisture resistance, powered | Per MIL 202G, method 106G  |
| Rotational life              | 8153: 50 million shaft revolutions with side load < 0.33 lb, 100 million with side load < 0.25 lb  All other models: 10 million shaft revolutions with up to 8 oz. side load |
| Storage temperature range    | -55°C to +125°C  |

### **Ordering Information**



#### Codes

| Voltage | Output | Codes |
|---------|--------|-------|
|---------|--------|-------|

Ingress protection rating (IP code)

| •  | •             |
|----|---------------|
| V0 | ≤ 3% to ≥ 96% |
| V1 | 4% to 96%     |
| V2 | 5% to 95%     |
| V3 | 10% to 90%    |
| V4 | 15% to 85%    |
| V5 | 20% to 80%    |
|    |               |

When V0 is used the angle specified is the theoretical angle over which the output would vary if the output could actually reach 0% and 100% of  $V_{\text{CC}}$ .

### **Optional Feature Codes**

|         | ·  |
|---------|--|
| No code | 8151, 8153 plain shaft; 8154, 8156 slotted shaft         |
| SS      | Slotted shaft (8151, 8153 only; not used for 8154, 8156) |
| FS      | Flatted shaft  |
| LT      | Linearity data   |
| SL      | Shaft lock (8156 only)                                   |
| CW      | Reverse direction  |
| НТ      | High torque (8156 only)                                  |
| ES      | Seal IP66 (8154, 8156 only)                              |
|         |  |

## Hall Effect, Non-Contacting Position Sensor

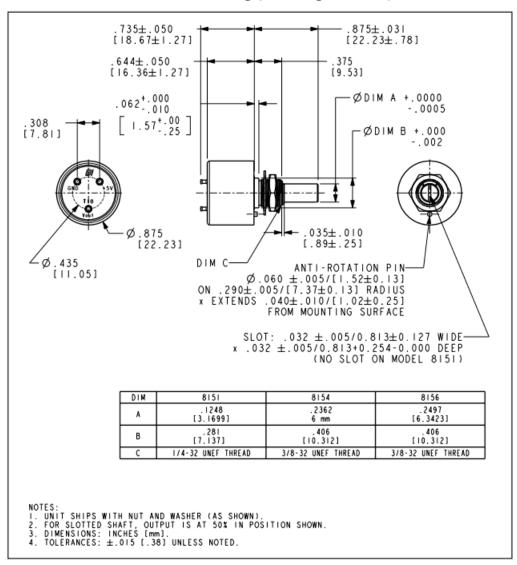


### **Matching Turns Counting Dials**

8151: RBJ, 2601, 2641

8154, 8156: RB, 2126, 2606, 2606S, 2607, 2607S, 2626, 2627, 2646, 2646S, 2647, 2647S

### **Outline Drawing (bushing mounts)**



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### **Outline Drawing (8153 servo mount)**

